

Action = Pattern Data * Timing Data (Limited by TimeSet) * Waveset * Drive

FIG._1

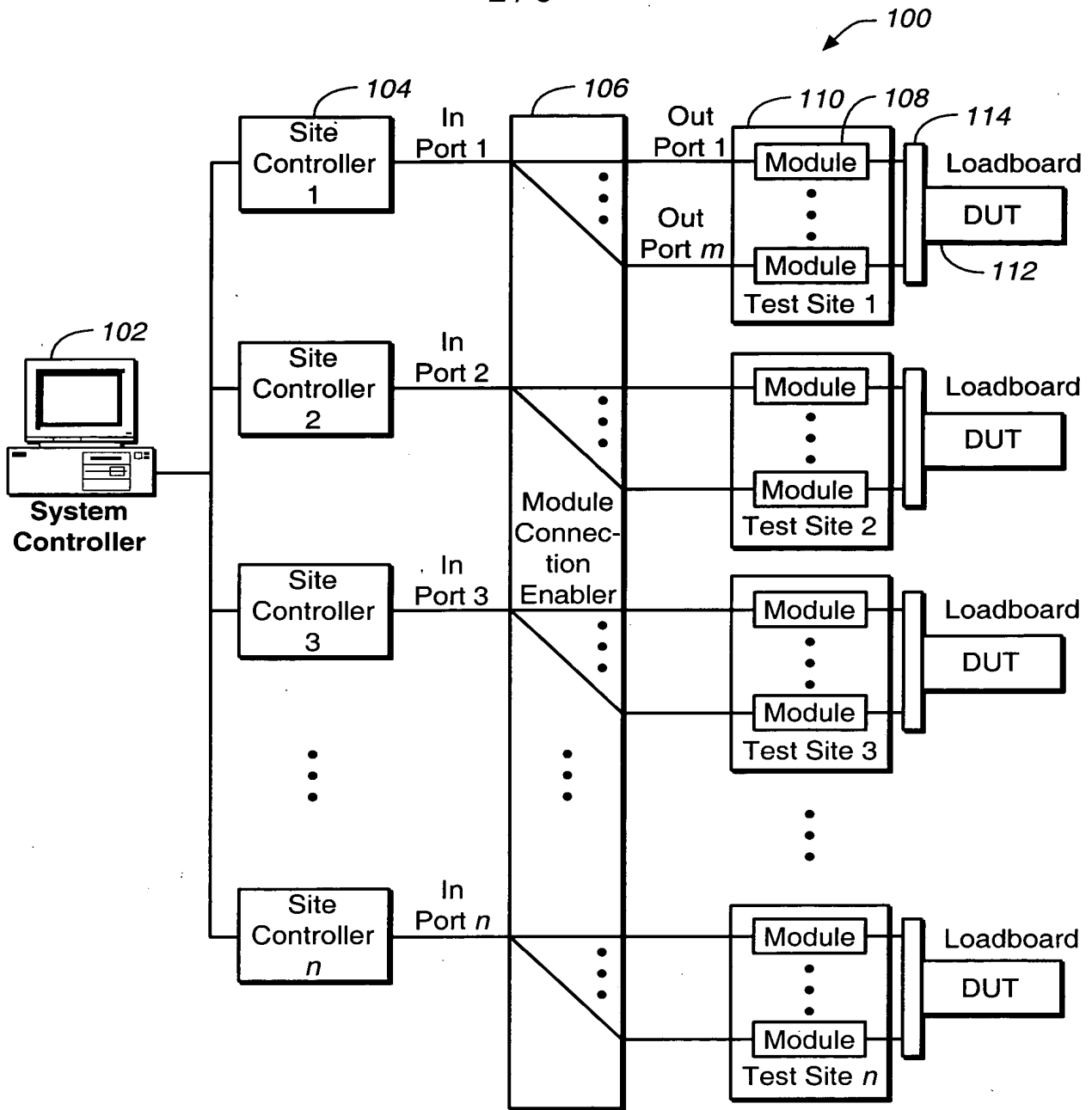


FIG._2

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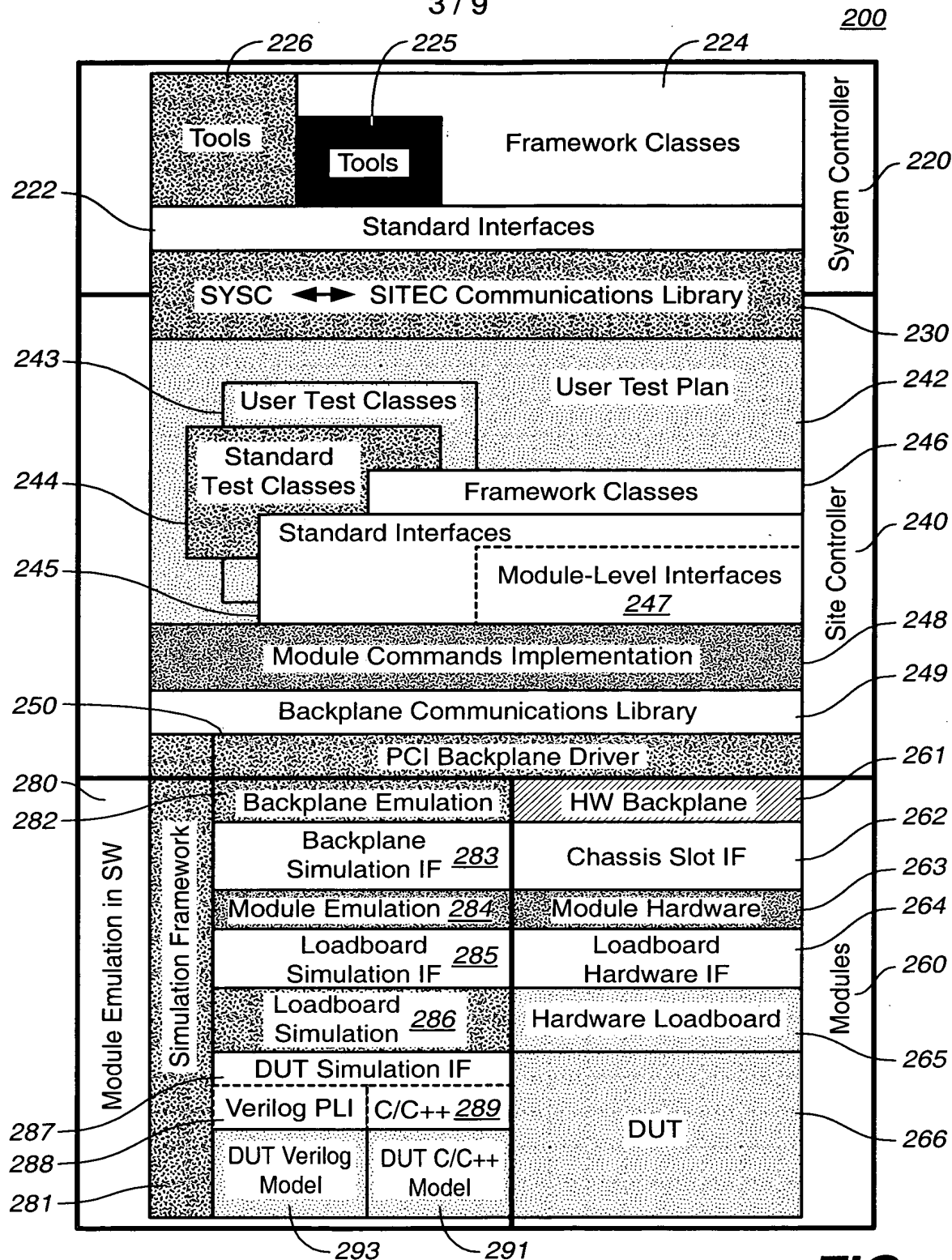
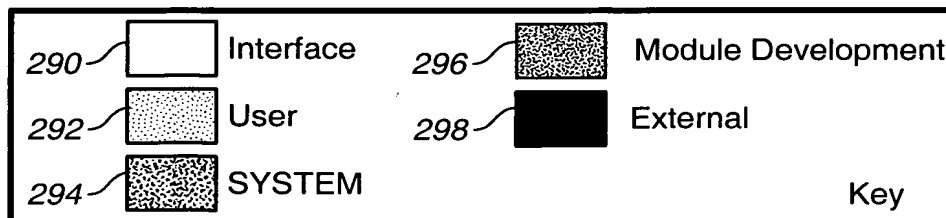


FIG._3



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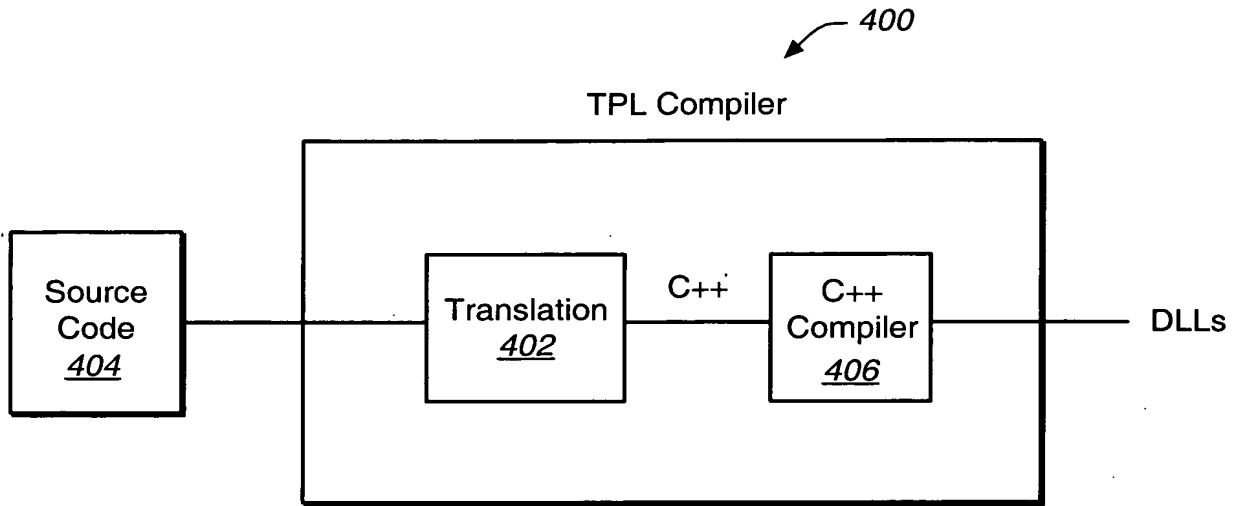


FIG._4

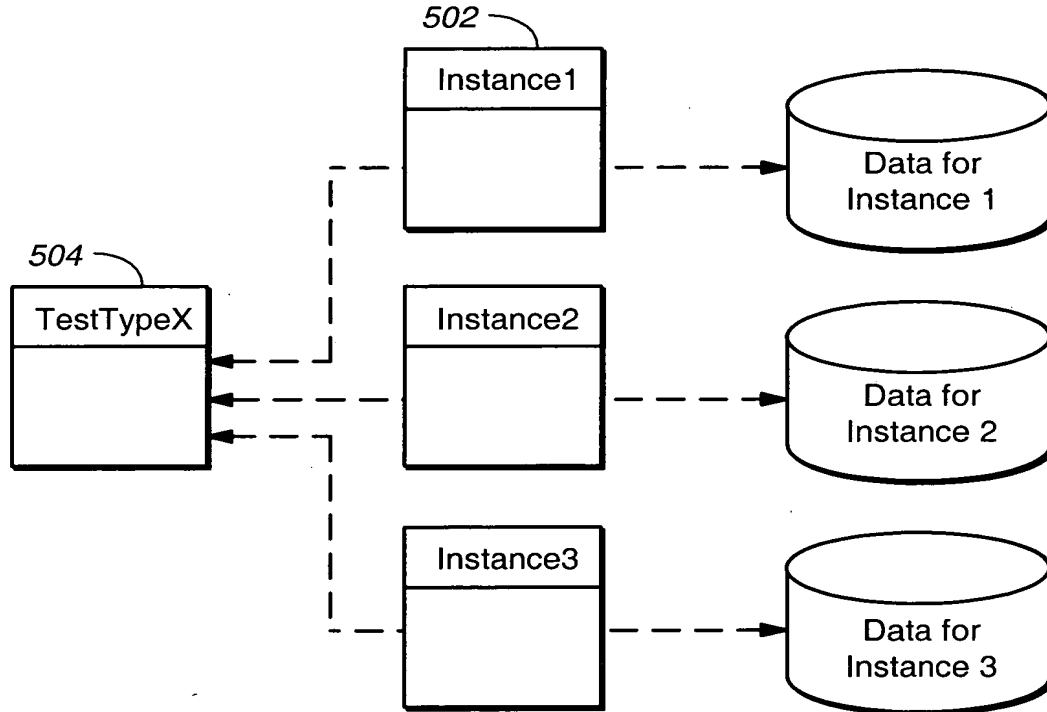


FIG._5

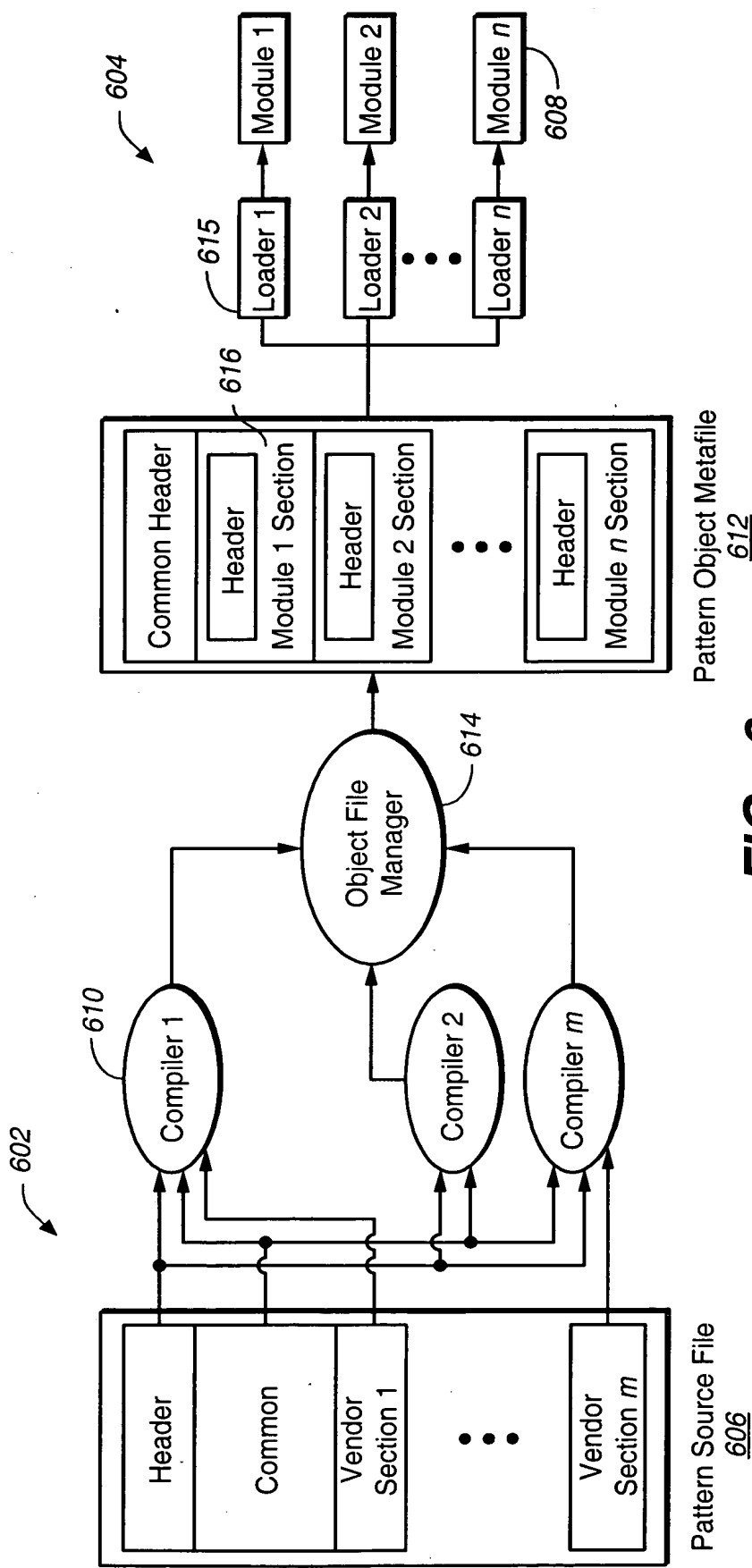


FIG. 6

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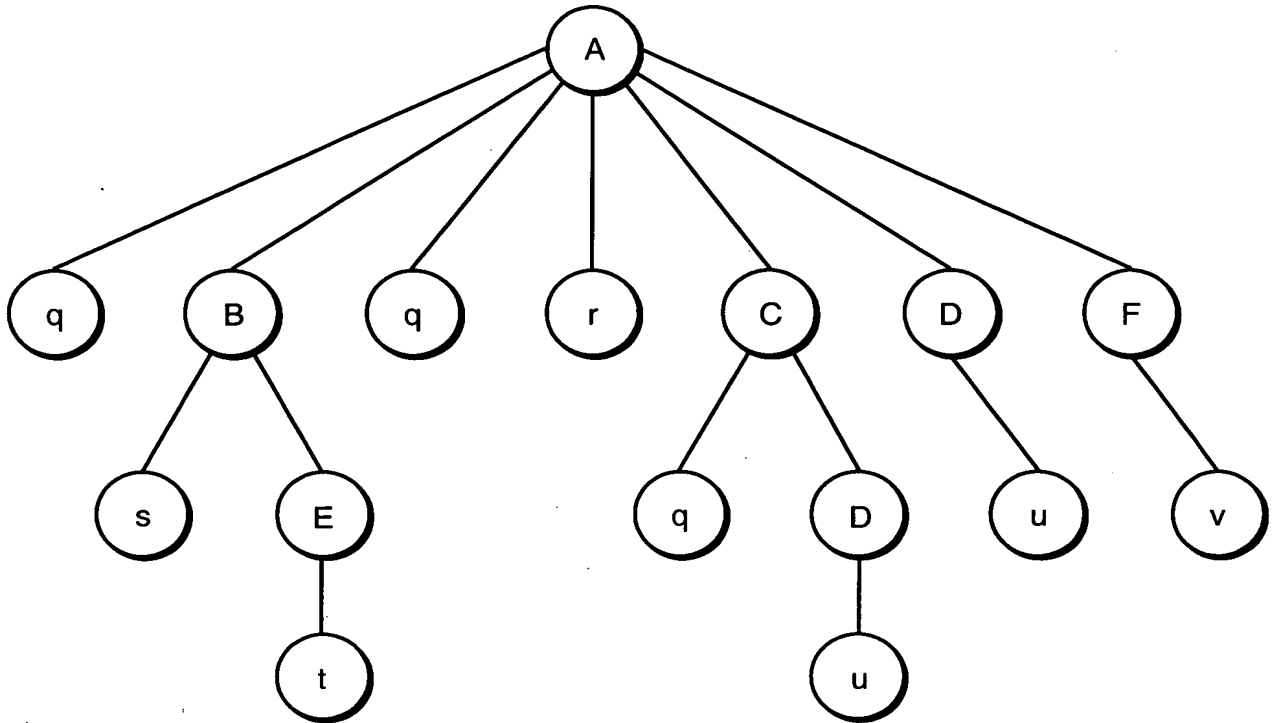


FIG._7

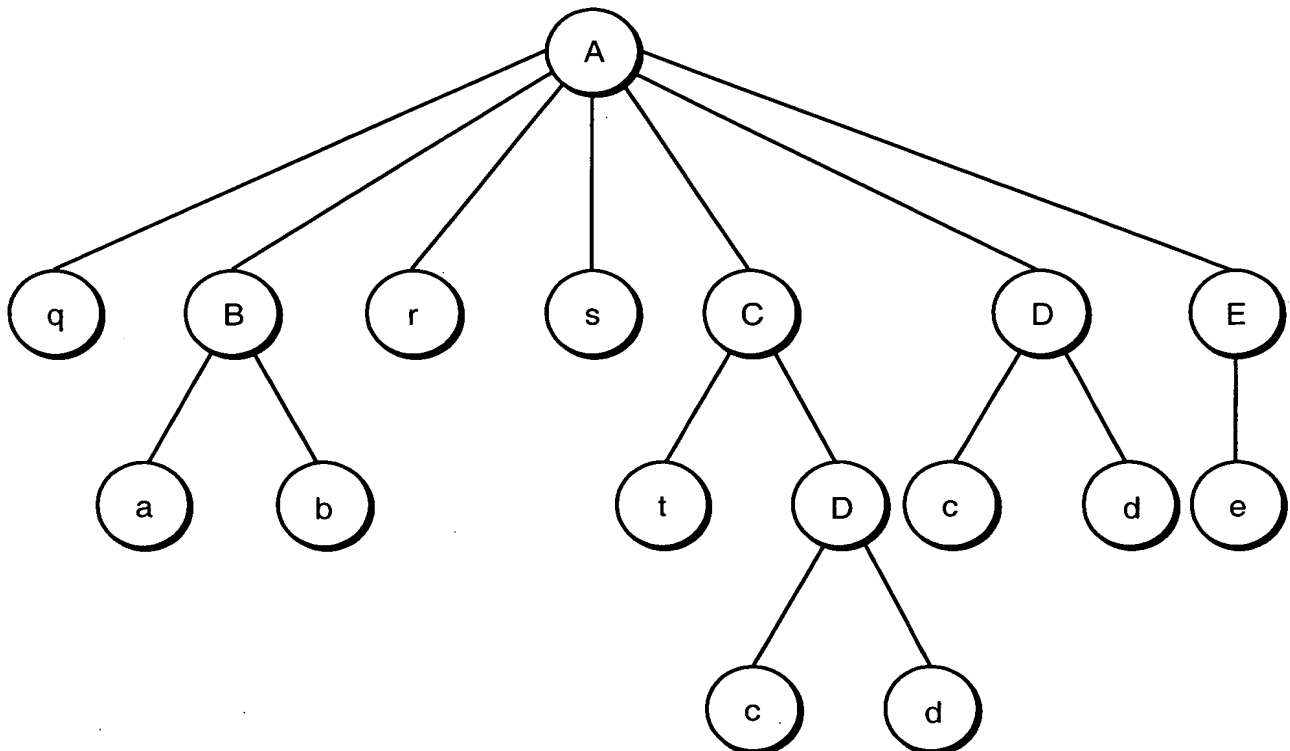


FIG._8

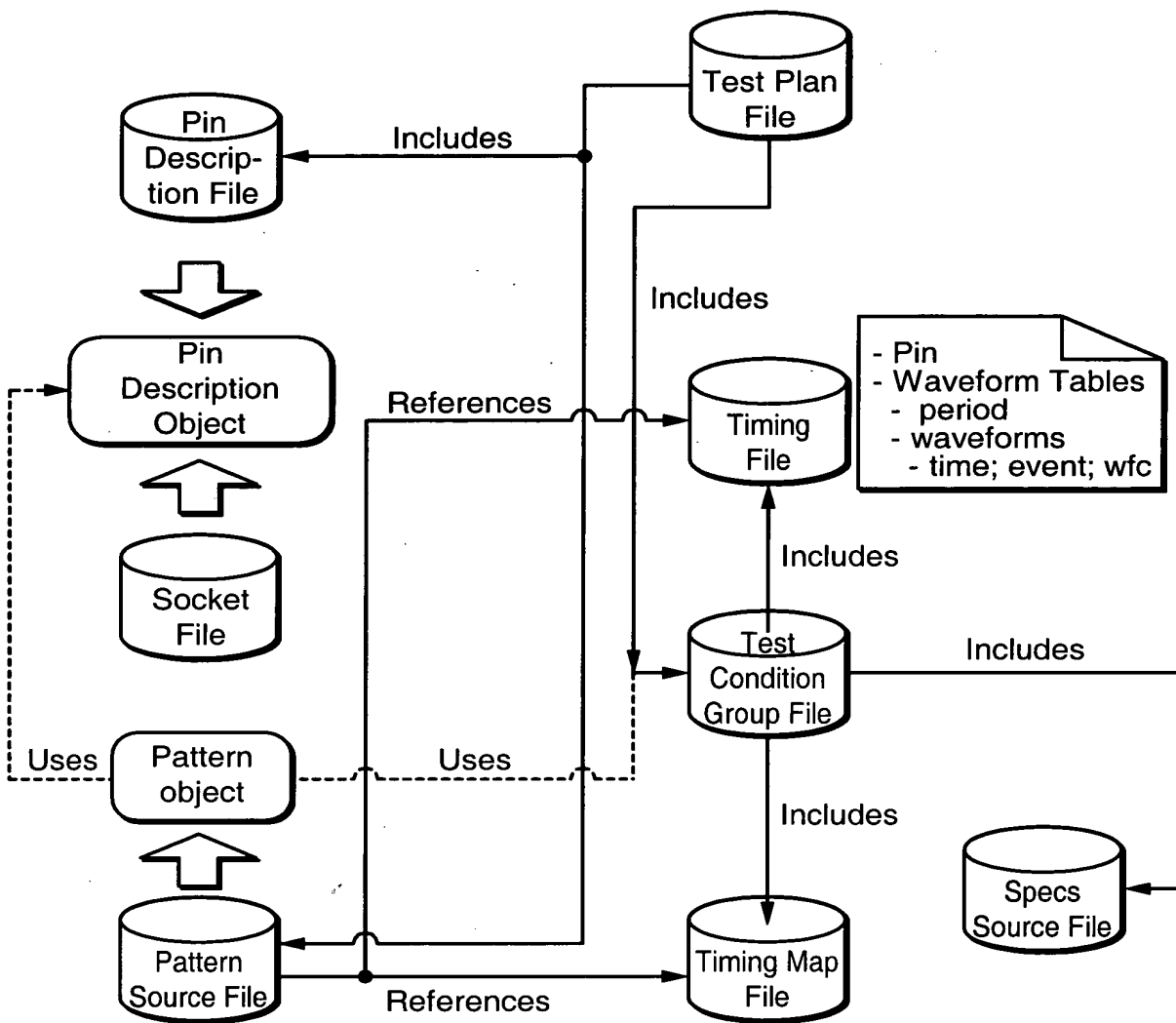


FIG._9

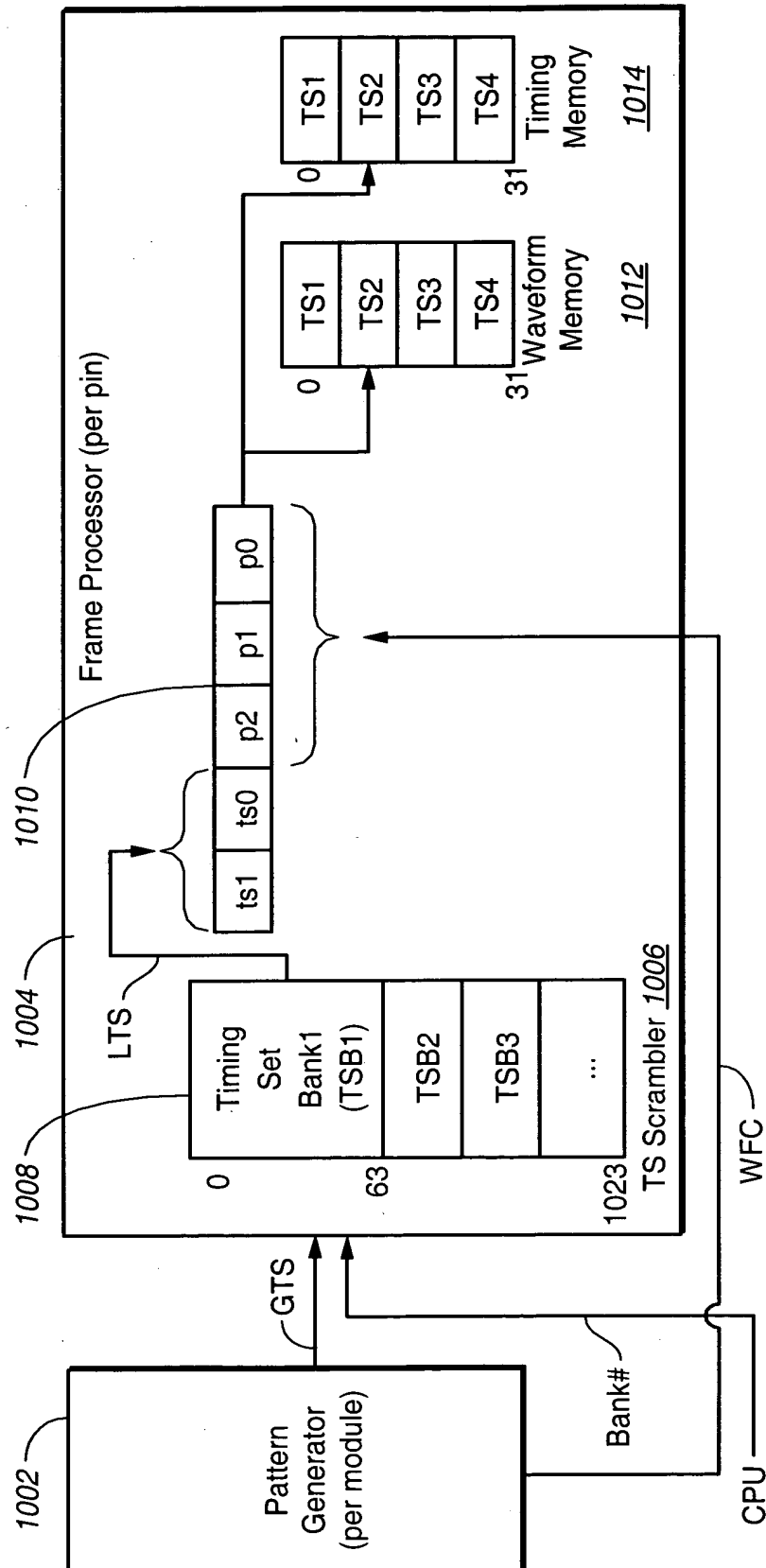


FIG. 10

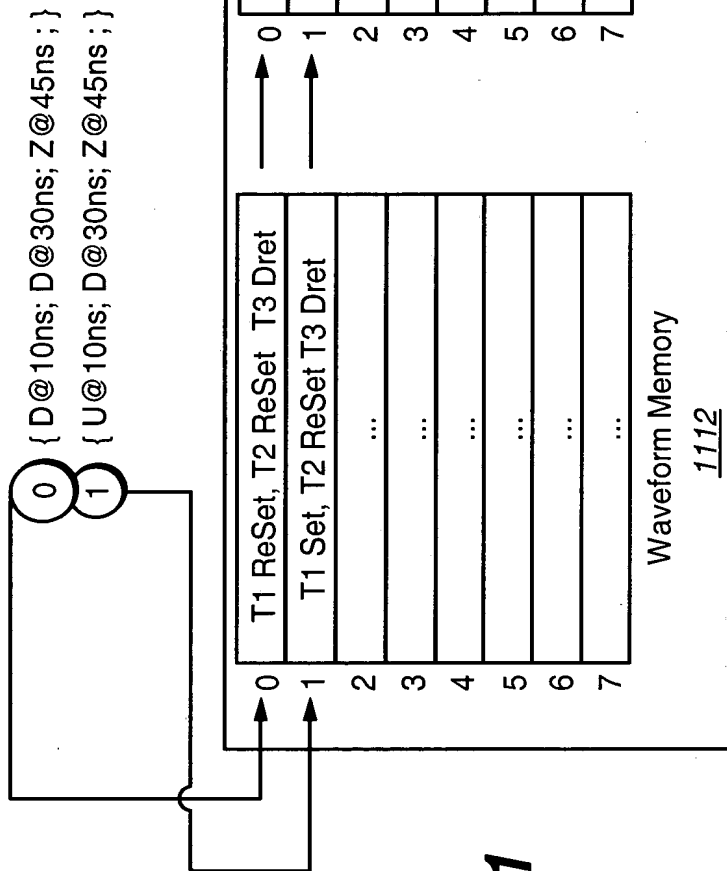


FIG. 11

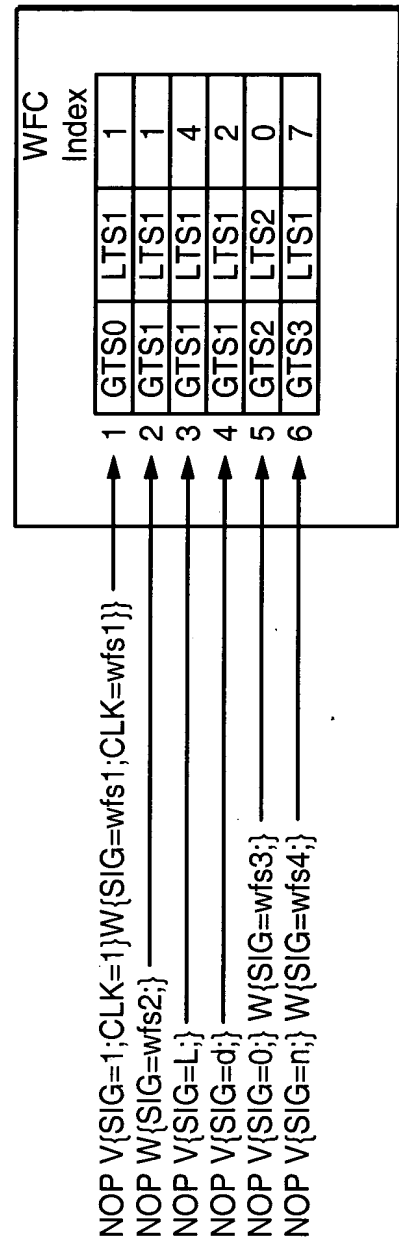


FIG. 12